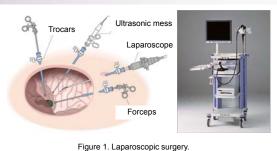
## Development of Blood Vessel Search System Using Near-infrared Light for Laparoscopic Surgery

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### SUMMARY

Accurate image processing and 3D blood vessel detecting technique is strongly required in the laparoscopic operation with minimally invasive surgery. Our detecting system adopts Near-Infrared (NIR) light and the stereo method. The blood vessel visualization system adopts hemoglobin's absorption characterization of the NIR light. A sharpening process is employed to improve the image quality of original ones taken by laparoscopic system. 2D location of the blood vessel is calculated by the stereo method using luminance distribution. Experimental results of depth obtained by our detecting system showed good agreements with the given depths, and the availability of this system is confirmed.



#### Objective

Development of Integrated system for Visualization of the blood vessel and 3D BVS.

#### Research theme

(a) Side of laparoscope

- (1) Blood vessel visualization using NIR Light and sharpness processing
- (2) Stereo method using NIR LED light and CMOS cameras to detect blood vessel accurately
- Blood vessel visualization system
  - 3D blood vessel searching system
- Contribution to reduce a blood vessel cutting accident by the human error of the doctor.

### LAPAROSCOPIC SYSTEM & BLOOD VESSEL PHANTOM

Image treatment scheme and Specifications

Measurement method: Using NIR –LED light (wave length:870 [nm]) and CMOScamera (300 thousand pixels) for peripheral blood vessel.

Cameras

VIR-LED

(b) Tip of laparoscope

2 type of blood vessel phantoms

16 mm

Figure 4. Phantom for VBS.

(a) Side of phantom

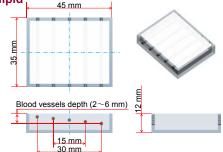
Figure 4. Blood vessel phantom using polycarbonate for 3D VBS.

Figure 5. Blood vessel phantom using intralipid

(b) Tip of phantom

for blood vessel visualization.

22 mm



Blood vessels

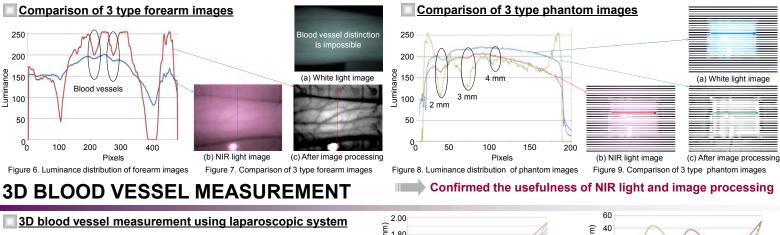
Figure 2. Blood vessel visualization

using NIR light

Figure 5. Phantom for blood vessel visualization

# BLOOD VESSEL VISUALIZATION

Figure 3, Laparoscopic system.



error (µm) E 1.80 20 Real value of 30 to 70 mm was measured 3 times. (Figure 10) SLIG 1.20 0 The error at 70mm is very large. -20 Measurement u.80 -40 Irem Correction of the measured value using the correction formula. 0.40 -60 Detection error was estimated as 80 µm. Mea -80 30 0 30 40 50 70 40 50 60 60 Real value (mm) Real value (mm) CONCLUSION Figure 10. Relationship with real value and measurement error Figure 11. Relationship with real value and correct error

Confirmed the usefulness of NIR and image processing in blood vessel visualization 🔤 3D BVS detection error was estimated as 80 µm

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